COIL WINDING MACHINE ERN T-VERSION

OPERATING INSTRUCTIONS

Version: 1.3

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ERN 100T, 200T



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1. INTRODUCTION

Floor type universal coil winding machine ERN is designed for winding heavy coils, transformers, chokes, resistors etc with wire up to diameter of - see technical data.

1.1 Characteristic features:

- 15" industrial capacitive touch screen for data display and programming
- wide range of application for winding simple or complicated coils, multi-chamber coils, trapezoidal or asymetric windings
- AC servo, that is used like a spindle drive assures excellent dynamical parameters, constant torque and accurate positioning
- wire guide on ball bearings, traverse drive servo motor
- accurate reversible turn counting
- microprocessor-controlled winding cycle without time waste
- wide programming options
- special functions LAYER-STOP, AUTOMATIC CORRECTION, MANUAL REGIME
- 4 programmable digital outputs
- 4 programmable digital inputs
- 40 GB programme store

-connection : 2x USB 2.0 1x USB 3.0 1x LAN

2. TECHNICAL DATA

ERN 100

Pitch range (mm/rev): 0,000 - 160 Winding width (mm): 400 - 800 - 1200 Winding speed / torque [rpm/Nm]: 600 / 75 300 / 150 Accuracy of spindle stop [rev]: 0.01 Spindle position pre-set [rev]: 0.01 Wire guide position pre-set [mm]: 0.01 Max.speed of wire guide - shift [mm/s]: 100 - winding 75 Acceleration/deceleration: table Max.coil diameter [mm]: 600 - 800 - 1000 Distance between centres [mm]: 800 - 1200 - 1600 Dimensions (mm): 740x1800 - 2300 - 2500 Weight [kg]: 600 - 750 - 900 Power supply [V/Hz]: 3 x 400 / 50-60 Power consumption [kVA]: max. 7 Noise [dB]: 74

0.000 - 160 400-800-1200 150 / 270 75 / 540 0,01 0,01 0,01 100 75 table 600 - 800 - 1000 800 - 1200 - 1600 780x1800 - 2300 - 2500 700 - 850 - 1000 3 x 400 / 50-60 max. 7 74

2.1 Climatic conditions

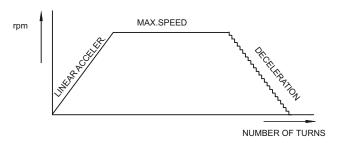
Machine is designed for normal workshop conditions with relative air moisture 70% and temperature in the range of +15 up to $+30^{\circ}$ C.

3. DESCRIPTION OF MACHINE

Coil winding machine ERN consists of the following parts:

- controller containing control electronics
- industrial PC with 15" touch screen
- drive unit containing servomotor with gears, pitch control unit with servomotor, power electronics and control elements
- base frame
- moving tailstock (optional tilting)
- universal wire guide (adjustable for round and flat wire)
- support with spool holders and dereelers (optional accessories)

Winding cycle (linear acceleration, max.speed, linear deceleration and stop) is running automatically after pressing the START-button. Deceleration is controlled by microprocessor to ensure accurate stopping and spindle positioning.



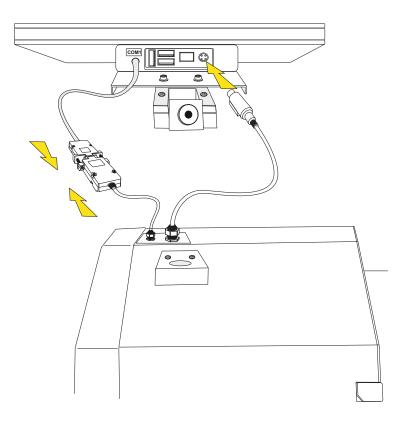
2 / ERN T / V 1.3

ERN 200

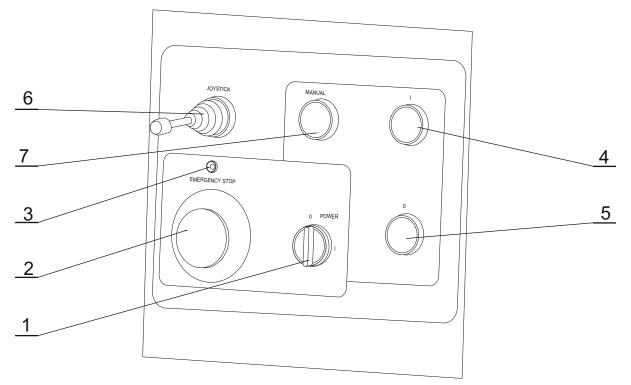
3.1 Description of controls

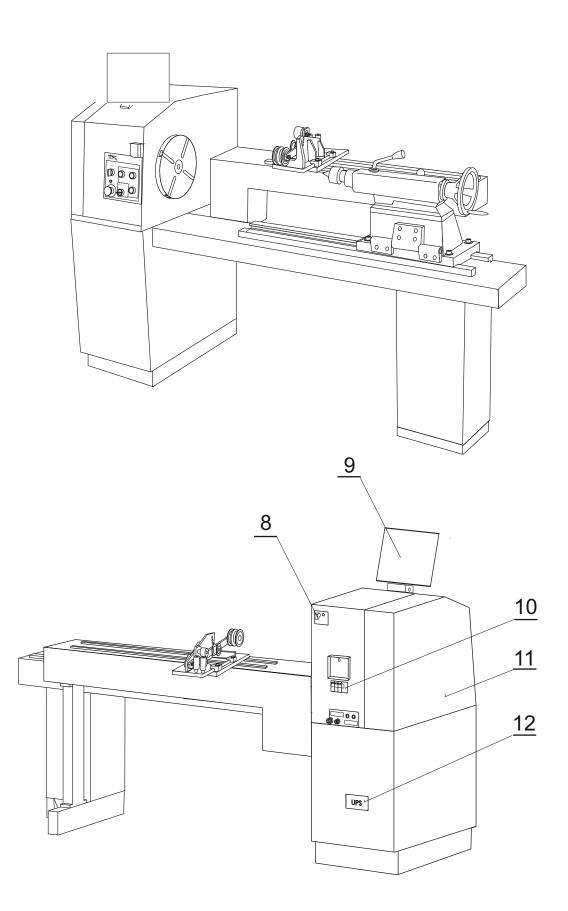
- 1 POWER ON / OFF switch
- 2 EMERGENCY STOP disconnects power in emergency
- 3 POWER ON indicator
- 4 START button starts the winding cycle
- 5 STOP button interrupts the winding cycle
- 6 JOYSTICK
- 7 MANUAL button
- 8 Connector for foot pedal
- 9 Industrial PC
- 10 AC circuit breaker
- 11 Gear cover
- 12 UPS

Monitor cables assembly



Control elements





3.2 Description of PC display

Display provides two basic views for standard information during winding: **Winding window** and **Programming window**.

Switching from Winding to Programming window it is necessary to touch central display place. Switching back - touch ENTER button.

WINDING 6 Step: ABORT STEP 25.30 NUMB GARDE POSITION BACK TOTAL Position: 22.34 NUMBER OF Next Step: 7 - SHIFT -Name: example4 m Pedal: 305 -THE 007 STEP NUMBER STEP NUMBER **Programming window** Step: 1 SHIFT 17.00 Gear: 500 .00 0 ed: 100 SHIF PROGRAM 17.00 CYCLE MENU PITCH SPEEC cu STEP NUMBER STEP NUMBER GEAR

Winding window

In order to work with a PC we can use the supplied mouse, which we plug into the USB port . Some advanced computer operations can be performed only with the mouse and keyboard.

4. INSTALLATION AND PREPARATION OF WORKING EQUIPMENT

4.1 Mechanical installation

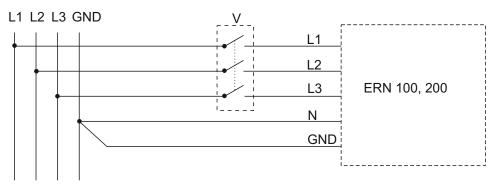
The winding machine is fixed to the transport wooden pallet. It is necessary to prepare a level balanced surface for its final location. The both frame surfaces must be balanced horizontal in one surface. The winding machine is moved by lifting at 3 pendant eyes. At the winding of heavy coils there is recommend to fix the base frame with screws M 12 directly to flooring surface.

4.2 Power connection

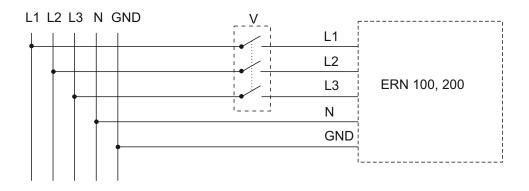
The machine must be connected to four- or five-wire system of the supply voltage 3N/PE400V/230V,50 Hz TN-S with tolerance +-5% and max. power consumption 7 kVA. Before plug in the connection cable make sure that electric power accordance with technical requirements. Only professional staff who are qualified in electrical engineering are allowed to install the power connection to the machine.

There is no guarantee for damages caused by wrong or out of range connection to the power supply.

Four-wire system - recommended connecting



Five-wire system - recommended connecting



An additional switch "V" is recommended to use in case, if the lead-in cable is fixly connected to the line distribution. If the moving terminal is used for the installation, this switch will be not necessary.

4.3 UPS

The UPS is alive constantly, if the main switch (10) is in off-position, as well. In common running the UPS must be switched on constantly. In case of continual fall-out loss of the line voltage, e.g. electric distribution breakdown, repairs and re-designs or when the running is dead, it is necessary to set the UPS to off, that the useless discharge of storage batteries does not arise. Press the buttons by instruction on label.

Repeated switch on is made by pressing the on button.

If the electric power supply was broken in the whole system - e.g. by setting the switch EMERGENCY STOP (2) to off, by the main switch (10) or the lenght of fall-out loss of the line voltage surpassed the battery capacity of the UPS (more than 90 minutes), the hard RESET will arise after renewing electric power supply. After pressing the ENTER button the last remembered data from EEPROM will be set up.

If the electric power supply is broken while winding, the spindle will stop and the winding machine switch over to the stand-by after few second. After renewing electric power supply the machine returns to the initial regime, but in the position like after pressing the STOP button.

Keep always the following order at switching off and on the winding machine:

- SWITCH ON: a) the UPS if it was off
 - b) the main switch (10)
 - c) the power on switch (1)
- SWITCH OFF: a) the power on switch (1), wait till the dark power on indicator b) the main switch (10)
 - c) the UPS only if it is necessary

4.4 Machine preparation for running

The machine operating is allowed only by skilled person who is acquainted with user's guide and safety formulas. The training is provided by producer or qualified person.

The machine is delivered partly disassembled for easier packing and transport. Before you switch the machine on, for the first time, assemble it as follows:

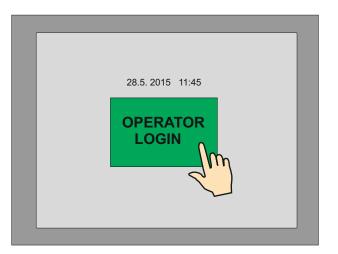
- a) Mount the display on the drive unit. Connect the power plug and serial interface.
- b) Check and fasten the fuse cartridges on the back panel of the drive unit
- c) Connect the foot pedal to the connector (8)
- d) The UPS (12) is switched on by pressing the button

Assembly is completed by this and prepared to work.

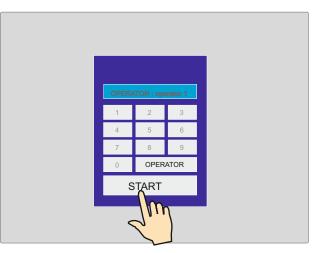
5. WINDING OPERATION

5.1 Switching the machine on and gear setting

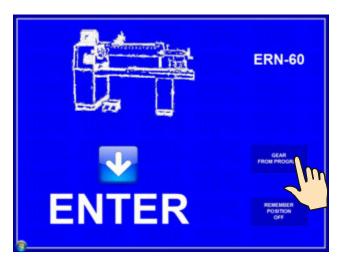
After switching on (1) the start window appears



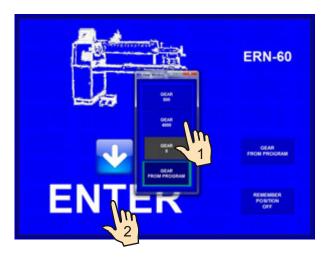
After pressing "OPERATOR" it is possible to choose operator name and continue by pressing START. This window appears only if you choose operator login (see chap. 13.)

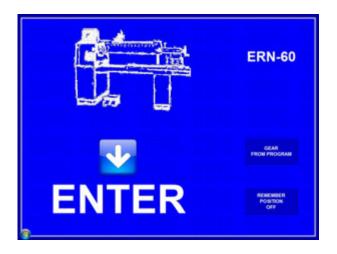


Display provides information about the type of machine the controller is set for. In this window the set gear can be changed.



The gear change requires the use of password - Master code (listed in the warranty card) as a confirmation that the change is done by an authorized person.



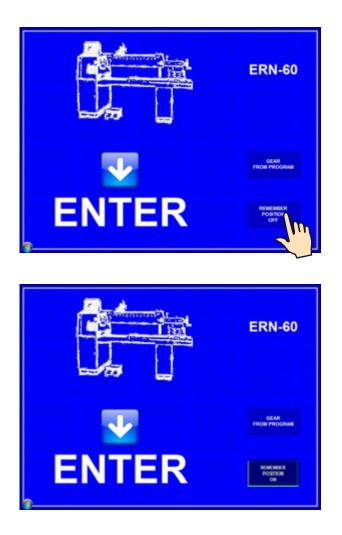


After pressing ENTER the initial setup is complete. This means that the wire guide is shifted to left home (zero) position - zero number of turns, step 0 and the last programme is set.



5.2 Backup of winding data in case of an electricity drop

In this window the initial setting of the machine (wire guide position, number of turns and step) can be activated.



After the activation of this function (MEM.POS.ON) will be updated with values as they were before the electricity drop.

IN ORDER TO USE THIS FUNCTION THE MACHINE MUST BE EQUIPPED WITH THE UNINTERRUPTIBLE POWER SUPPLY UNIT (UPS) AND THE REPORT OF ELECTRICITY DROP (relay for POWER) MUST BE INSTALLED. IF THE MACHINE IS NOT EQUIPPED WITH THIS, THE INITIAL SETTINGS WILL BE SET TO ZERO VALUES.

5.3 Winding and programming window

There are two basic windows.

Actual state Winding corrections Step 2 WINDING Step 500.00 Gear 6000 Number of turns Wire guide position and direction Position Next step Next Step: • 1 - SHIFT Steps list Name: Pokus1 Terminal Coil name Exit Pedal: PROGRAM STEP Step change Pedal speed TEP NUMBER ALCONE . Joystick

<u>Winding window</u> - provides actual information about the winding process

Programming window - displays the view of programmed step parameters

Step: Gear:		2		NDING 00.00			
Choose	step r	numbert	500	. 0	0	0	
	8	9	WINDING 500.00	SHIFT	JUMP	DELAY	PROGRAM
4		6	РІТСН	CYCLE	SPEED 5003 [11]	FUNCTIONS	MENU
			1.000	÷	5		antino
0		CLR	50.00	100.00	INPUTS	PEDAL	сонистоя
	ENTER		STEP	NUMBER	STEP N	UMBER	GEAR

Winding is possible only in these two windows and STEPS LIST window . If any other window is opened, the cycle start is blocked.

5.4 Explanation of concepts STANDSTILL, START, STOP

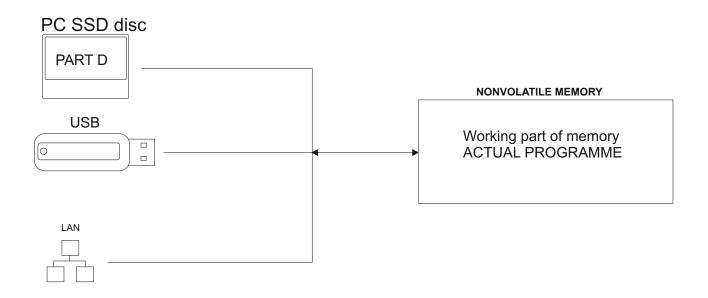
STANDSTILL: State after switching on the machine and pressing ENTER, or after a step finished. Starting from this state will shift the programme one step forward. Eg.: If we are in the step 0, after pressing START, step 1 will be running.

START: Active run of some step type (winding, shift, jump and pause).

STOP: State after pressing the STOP-button (cycle interruption). Pressing the START-button again will reactivate the interrupted cycle. There is no step shifting.

5.5 Winding programme selection

The winding programme we are currently using with (winding or programme creation can be performed) is called **ACTUAL PROGRAMME**. Actual programme is located in so-called working part of memory. Desired winding programme can be loaded to the working part of memory either from PC memory, USB flash drive or a LAN network.



Proceeding with programme selection: see section 9.

Data store in the working part of memory will remain there even if power is disconnected!

5.6 Start and Stop of winding cycle (programme)

Winding cycle is initiated by pressing START-button (4), or foot pedal. It is possible to start programme from each step. Required step is set up

by the touch buttons

STEP NUMBER

, numeric keyboard or joystick.

STOP-button (5) interrupts the winding cycle. It is the priority button, which means, that the cycle interruption at incorrect time (while deceleration), may cause inaccurate stopping and positioning of the spindle.

Cycle interruption at the step "Winding" allows almost all corrections and adjustments.

5.7 Foot pedal

Winding machine may be equipped with the following types of foot pedal:

Double foot pedal controls START, BRAKE RELEASE

- left pedal releases the spindle brake
- right pedal works in parallel with the START-button

Double foot pedal controls SPEED, BRAKE RELEASE

- left pedal releases the spindle brake

- right foot pedal controls spindle speed depending how hard the pedal is pressed.

Maximum speed, acceleration and deceleration ramp can be set up by PEDAL button.



Speed set up in this way is applicable only for the current programme. It is independent of the speed programmed in a specific programme step. Eg.: maximum speed set up by START pedal may be differ to maximum speed set up by START button.

There is a time delay 0,5 sec between repeated presses for safety work to prevent unintended start of the next step.

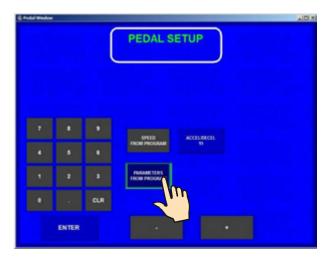


Accel.	and	dec.	ramp	for	pedal
100001.	ana	acc.	ramp	101	pouur

CODE	ACC.TIME (sec)	DEC.TIME (sec)
1	1,0	0,5
2	1,6	0,8
3	2,4	1,2
4	3,0	1,5
5	4,0	2,0
6	5,0	2,5
7	6,0	3,0
8	8,0	4,0

Acceleration and deceleration ramp values are always taken from window PEDAL SETUP.

If we require the same maximum pedal speed as speed programmed in the current programme step, we need to press the PARAMETERS FROM PROGRAM button.



Max. pedal speed is controlled by values programmed in individual programme steps.

Winding cycle start continuity

This option is utilized during winding start. Wire application and winding of the first turns is done by pedal and then by pressing START button (4) cycle continues. Winding cycle can continue seamlesly without interruption.

5.8 Security measure – OPTO-SENSOR

OPTO-SENSOR TURCK type QMT42VN6FF1000 with range of 1 m (2 m), which logs body moves, is placed in a spindle axis in front of the workspace.

Sensor function is set not responding by low speed. It makes possible for operating staff to do specific operations, e.g. taping.

From 25 rpm is the sensor activ and it stops the winding machine by ray break. Marginal speed is to be programmed by PC and SERVOSTAR-software. The winding machine can be activated by pressing the button START then.

5.9 Winding corrections

Program corrections and adjustments are allowed only in the state "STANDSTILL" or "Winding STOP". Keys are blocked in other states.

5.9.1 Spindle reference position setting

The spindle can be positioned in the range + - a few degrees and exact position is kept for any amount of windings.

Reference (zero) spindle position is set up as follows:

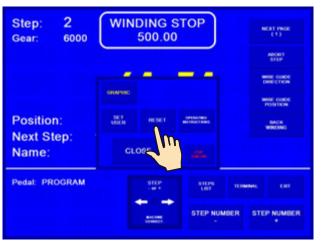
- switch the brake off by the switch (6)
- turn the spindle manually to the required position and return the switch (6) to the former position
- press EXIT and then RESET

OR

- press correction button ZERO SPINDLE POSITION 5.9.10 (new spindle position was changed without machine reset)

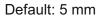
Note: When you switch the machine ON (by switch POWER or EMERGENCY STOP), RESET is running automatically and the spindle position is taken as reference position.

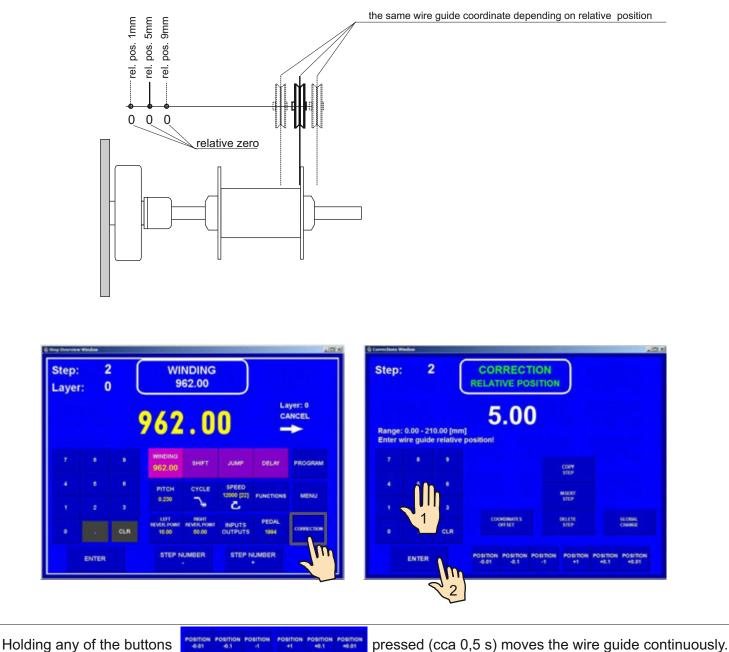




5.9.2. Wire guide relative position setting

This correction shifts zero coordinate of the wire guide (relative zero position). It allows you to correct the wire guide position to be in accordance with the bobbin or winding tool.

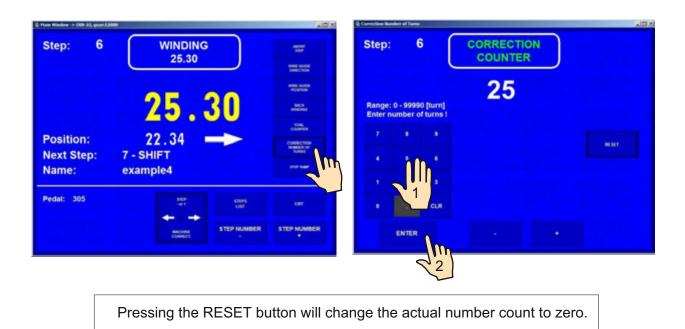




5.9.3. Number of turns correction

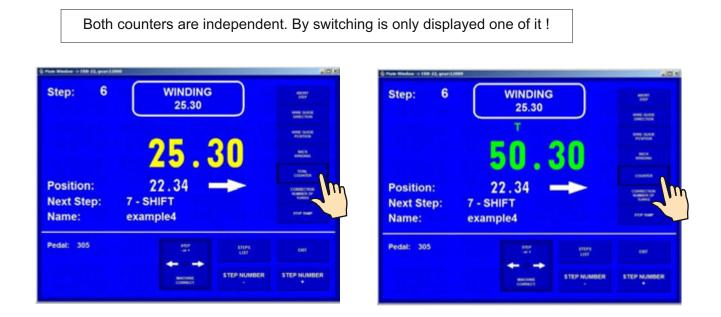
It is possible to change the number of turns actually counted.

Correction of decimal and hundredths turn number e.g. XX.36 to XX.30 without adequate spindle turn, leads to the loss of reference position.



5.9.4 Total counter

We can switch between TOTAL COUNTER and COUNTER. TOTAL COUNTER counts all spindle turns until it is set to zero by RESET, or is set differently by numeric keyboard.



5.9.5. Wire guide correction

This allows you to correct the wire guide position during the winding process.



5.9.6. Wire guide direction change

This allows you to change the direction of wire guide during winding.



5.9.7. Abort step

This allows you to abort current running step.

By pressing the ABORT STEP button the machine will return to the STANDSTILL state.



5.9.8. Back winding

This allows you to wind back the required number of turns.

Step: 6	WINDING STOP		Step: 6 BACK WINDING	
Position: Next Step: Name:	23.73 21.87 7-SHIFT example4	MERCENT MERCEN MERCEN MERCENT MERCENT MERCENT	Position: 19.88 Next Step: 7 - SHIFT Name: example4	
Pedal: 305	Entry List List STEP HUMBER	INT STEP NUMBER +	Pedal: 305	

We can wind back the number of turns required only by using the pedal. The number of turns is counted back and the wire guide moves in opposite direction.

Pressing of button "WINDING" ends back winding.

5.9.9. Deceleration ramp for the STOP-button

Deceleration ramp for the STOP button can be set. This ramp is slightly faster than programmed deceleration ramp. This is controlled by the software.



Code table

CODE	TIME (s)
1	1,0
2	1,3
3	1,8
4	2,3
5	2,8
6	3,8
7	5,8
8	7,8

Presentated values are valid for max.speed.

5.9.10. Spindle zero position

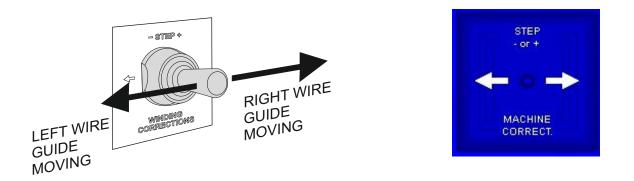
This allows you to taken new spindle zero position without machine reset, counter is canceled.



6.JOYSTICK

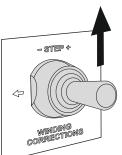
Each model is equipped with a four way JOYSTICK which provides the following actions:

- wire guide corrections

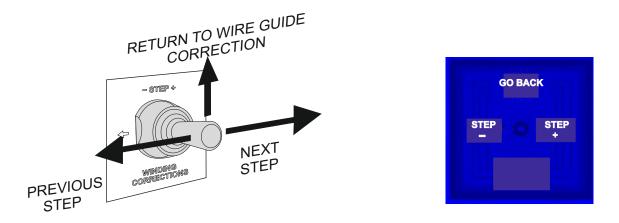


Holding the left or right position pressed (cca 0,5 s) moves the wire guide continuously.

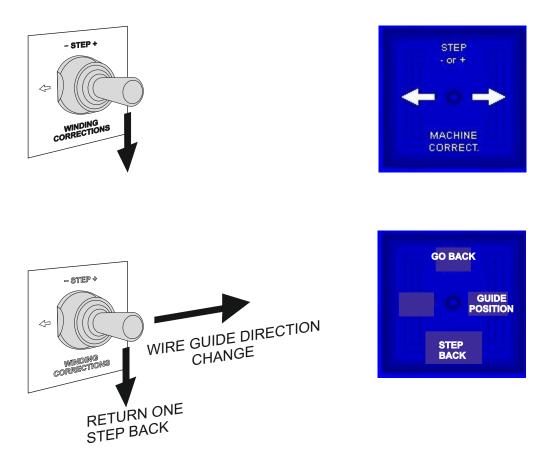
- step change







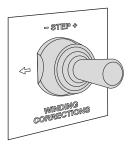
- return one step back and wire guide direction change

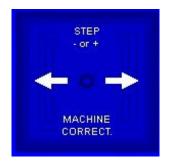


RETURN ONE STEP BACK - this action returns winding programme to the end of the previous step, and sets correct positions of the wire guide and the spindle.

JOYSTICK returns from this state to the wire guide correction after 3 seconds automatically

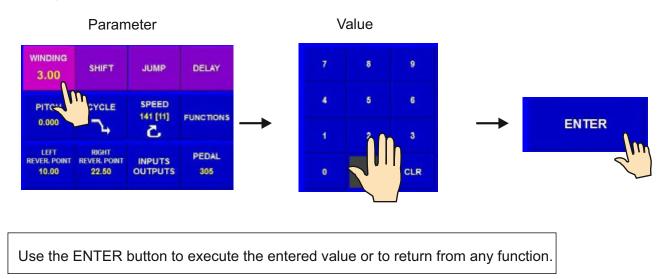
After 3 seconds





7. PROGRAMMING

Entering the data:

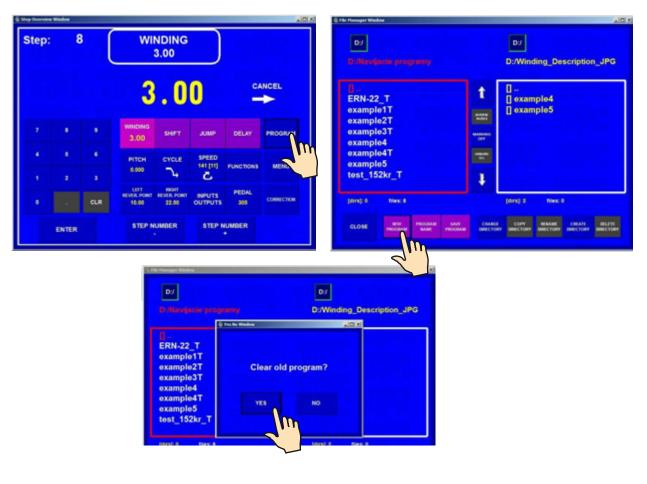


Programming is not possible in step 00. In order to move to a particular step, either use the

STEP NUMBER

or use the numeric keyboard.

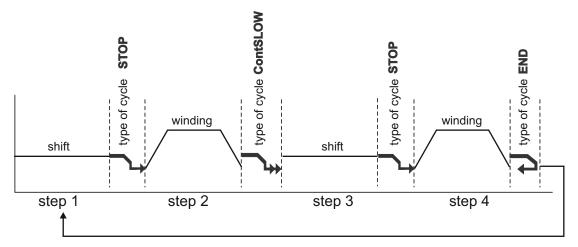
Created programme is saved to the working part of memory (programme in this memories is designated as an ACTUAL PROGRAMME). We can either overwrite (or modify) the already existing programme, or open the new one.



Step: 0			ADDAT STAF	Step:	1		EMP	TY STE	P		
	0.0	0	NINE CORE POSITION NINE CORE				0	.0	0		
Position:		-		×.	•		WINDING	знят	JUMP	DELAY	PROGRAM
lext Step: lame:	1 - EMPTY STEP		Tores a	×		•	ятсн	OYOLE	SPEED	FUNCTIONS	MENU
edal: PROGRAM		ESS PS LAUT	1997. :	1. 0		3 CLR	LEFT REVER PORT	NEAL POINT		PEDAL program	connection
	MACHINE COMMENT	STEP NUMBER			ENTER			UMBER		UMBER	

7.1 Basis of programming

The winding programme is a logical sequence of a few (1-350) joined steps.



Joining to the next step is defined by the type of cycle. If the type of cycle "END " is programmed within a specific step, this will end the programme. After pressing START the programme will restart at step 1.

Max.step capacity for one winding program is 350 !

7.2 Step parameters programming

7.2.1 Basic step types

Every step can be programmed as SHIFT, WINDING, JUMP, DELAY or GEAR.

- Shift spindle is not turning and the wire guide is shifting to the programmed coordinate
- **Winding** defined by the following parameters: number of turns, speed and spindle direction, pitch, left and right reversal point
- **Jump** spindle is not turning and the wire guide is shifting from its position to the left or right, in accordance with the programmed value
- Delay spindle and wire guide are idle, the duration of the pause depends on the programmed time
- Gear setting of requested gear, provides change of gear during cycle

7.2.2 Wire guide shift

Coordinating of the shift



Speed of the shift

The speed of shift is preset to 100 mm/sec during the programming stage. If lower speed is required, this can be changed as follows:

Step:		1 (s	HIFT			1950 1950
	0.00 - 2	10.00 (mm	0	.00		E	
			WINDING	SHFT 10.00	3,000	DELAY	PROGRAM
			PITCH	CYCLE	SPEED	FUNCTIONS	MENU
				÷			
		CLR	LEFT REVER POINT	REALT REVER POWE	INPUTS OUTPUTS	PROGRAM	CONFECTION
	ENTER						

Type of cycle

Set the type of cycle and choose, how to continue to the next step.



End of program

By pressing START-button, program is restarted and step 1 is running.



Cycle stop After step finish, program stops and the next step is activated by START-button.

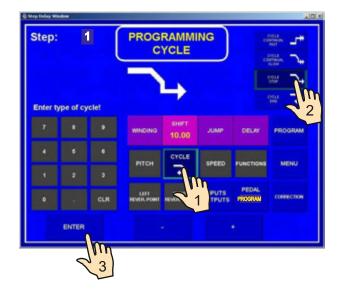


Continual cycle with deceleration After step finish, program starts the next step automatically, without pressing the START-button. Winding step decelerates to zero, at first.



Continual cycle without deceleration

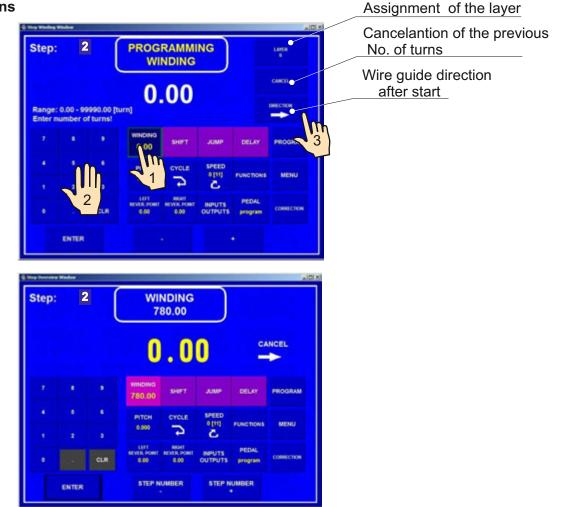
After step finish, program starts the next step automatically, without pressing the START-button. Spindle deceleration is canceled. Only winding steps can form this cycle.





7.2.3 Winding step

Number of turns



Cancelation of the previous number of turns

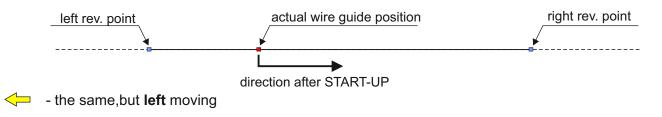
CANCEL - previous counted number of turns is cancelled after START-UP of the winding step type

NOT

CANCEL - counted number of turns is not cancelled

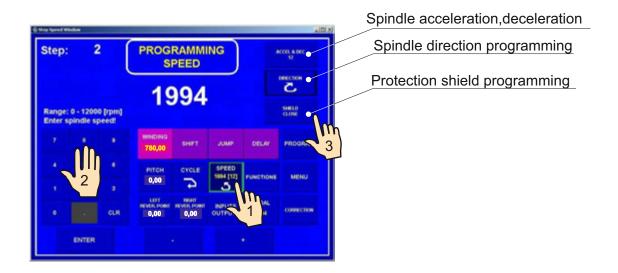
Wire guide direction after start

-right moving the wire guide after START -UP if its position is between left and right reversal point



If "**0** " is programmed for the number of turns, this winding step turns the spindle to the zero reference position. Direction of the spindle speed is taken from the previous winding step !

Spindle speed ,direction ,acceleration ,deceleration, and protection shield



Enter values between 1 and 8 for acceleration and deceleration according to the table below:

CODE	ACCEL.	DECEL.
	(s)	(s)
1	3,0	3,0
2	3,5	3,5
3	4,0	4,0
4	5,0	5,0
5	6,0	6,0
6	7,0	7,0
7	8,0	8,0
8	9,0	9,0

Pitch



Left reversal point



tep	2	2 PROGRAMMING RIGHT REVER. POINT							
ange		10.00 [mm ersation p	1	.00					
			WINDING 780.00	SHIFT	JUMP	DELAY	PROGRAM		
		8	рітсн 0.200	CYCLE	SPEED 1994 [12]	FUNCTIONS	MENU		
			un	C4 1000	2				
		CLR	10.00	0.00	INPUTS OUTPUTS	1994	CONFECTION		
	ENTER		POSITION P						

Right reversal point



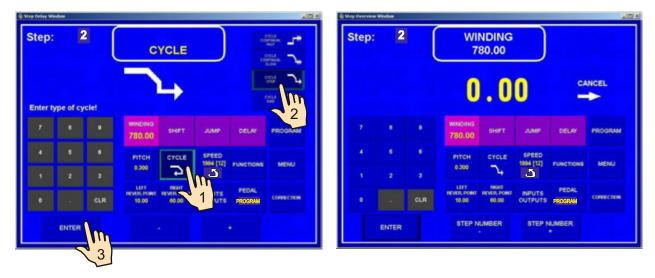
Switching OFF the wire guide shifting during programming

The wire guide shifting can be switched OFF by pressing the SHIFTING ON/OFF button during programming.



Type of cycle

Set the type of cycle and choose how to continue to the next step.

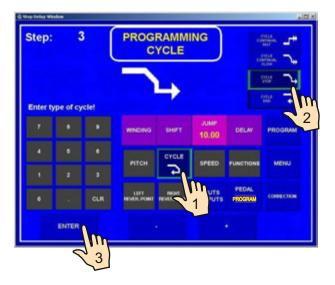


7.2.4 Wire guide jump

Lenght of jump and direction



Type of cycle



Step:		3		UMP 10.00			
			0	.0	0		•
		×	WNDING	SHIPT	зиме 10.00	DELAY	PROGRAM
4	•	*	ятсн	CYCLE	SPEED	FUNCTIONS	MENU
		CLR	LUTT REVER, POINT	RECHT REVER, POINT	INPUTS OUTPUTS	PEDAL PROGRAM	CORPECTION
	ENTER		STEP N	UMBER	STEP N	UMBER	

7.2.5 Delay

Time of delay



Type of cycle

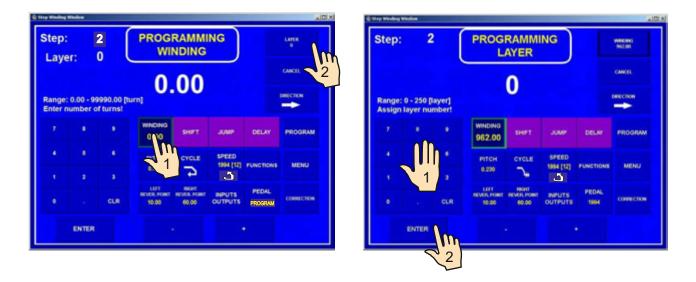
Step:	- 4	(-	YCLE		a.	* Dia * 1
		,	1				ر بر چ
Enter typ	e of cys	clet		7			
			WINDING	SHIFT	3,049	DELAY	PROGRAM
						1200	
			РІТСН	CYCLE	SPEED	FUNCTIONS	MENU
			LIFT REVER POINT	REAL POIN		PROGRAM	consection
<u> </u>		CLR	NEVER POSIT	HEVER POR	UTS		
	INTER						
	-	1111					
	5	3					
🕼 Stap Derreien W	indow	3					د التاني
Step:	veter 4			ELAY 1200			
) 0		(Dia
				1200	0 0	DELAY 1200	PROGRAM
Step:	4			1200 . ()	JUMP	1200	PROGRAM
Step:	4	•	0	1200 . 0		1200 FUNCTIONS	
Step: 7 4	•	•		1200 . 0	JUMP	1200	PROGRAM

7.3 Display and assignment of the layer

The number of layers can be displayed . Readout showed on display can be switched as follow :



The layer number of every step can be assigned according to winding instruction. The same number of layer can be assigned to a few consecutive steps. While winding, the assignment is displayed as it is programmed.





7.4 Programming corrections

The following functions simplify programming or corrections.

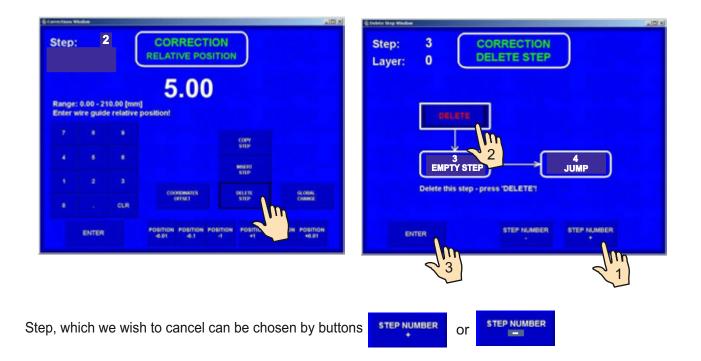
7.4.1 Insert empty step

An empty step can be inserted anywhere within the programme. It can then be completed with the required parameters. Subsequent steps are shifted in value " +1" automatically.



7.4.2 Delete step

Each step in the programme can be canceled. Subsequent steps are shifted in value " -1" automatically.



7.4.3 Copy step

Each already programmed step can be copied to another step (previous or next).

vections Window	X Dia	🕲 Copy Step Window	
tep: 2	CORRECTION RELATIVE POSITION	Step: 2 CORRECTION COPY STEP	
ange: 0.00 - 210.00 (m	5.00		
inter wire guide relative			
	CONY		
	HEARE T		TEP
		Copy this step - press 'COPY'	_
e . CLR	OPET STP OWE		
	POSITION POSITION POSITION POSITION POSITION	STEP NUMBER STEP 1	IUMBER
ENTER	0.01 0.1 ·1 +1 +0.1 +0.01	ENTER STEP NUMBER STEP	-
			m
			1

Current step is copied and inserted to the step, which can be chosen by buttons or or or

7.4.4 Global change

This function allows you to change one chosen parameter in all the subsequent steps. These must be of the same type. Eg.: if the current step is winding, the chosen parameter will be changed in all subsequent winding steps. This is valid for all other step types (SHIFT, JUMP, PAUSE).



Choose a parameter to be changed - eg. pitch



The pitch is changed in all the subsequent winding steps.

7.4.5 Coordinate offset

This correction provides offset for all coordinates in the programme to the left or right of the entered value.

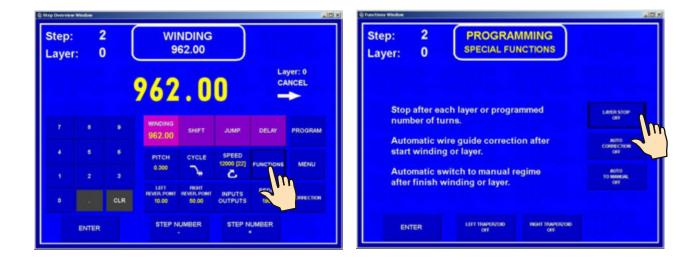


All programmed coordinates (left,right reversal points and shifts) are increased by the value of 20,0 mm.

7.5 Special functions

7.5.1 Layer stop

This function activates winding step STOP after each wound layer.



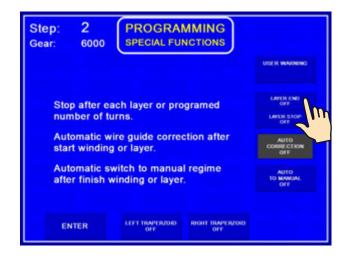
The machine will stop after each layer at both left and right reversal points. This will continue until the programmed number of turns is reached.

If the assigned layer is displayed, this function will increase its value automatically after each layer.



7.5.2 Layer end

This function activates winding step STOP in desired layer in reversal point.



The machine will stop in desired layer in desired reversal point and the entire winding step terminates.

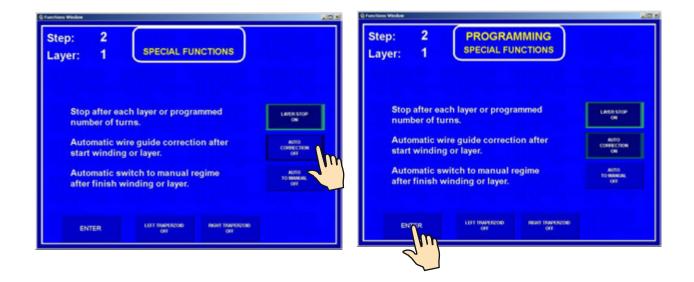
7.5.3 Warnings

This function allows to write important warning for any step. It shows automatically after step finish and disappears after next pressing START (or pedal).

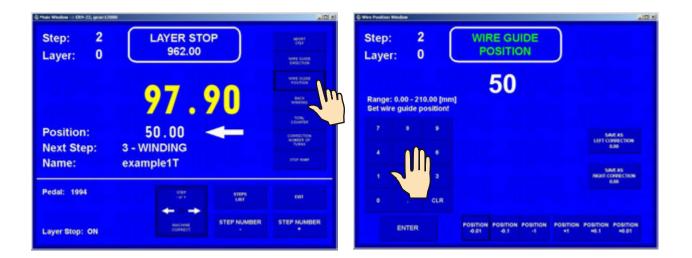
Step: 2 Gear: 6000 PROGRAMMING SPECIAL FUNCTIONS		Step: 2 Gear: 6000)
		WADNING	www.	Canadama
Stop after each layer or programed number of turns.	OFF	WADNING	WARNES	WARMAG
Automatic wire guide correction after start winding or layer.	AUTO CORRECTION OFF	WINDING	WARNES	WINDOWING
Automatic switch to manual regime after finish winding or layer.	AUTO TO MANUAL OFF	WARDING	WARNING	WARNING
		WARNING	RATING	WARNING
ENTER LEFT TRAVERZOID BIGHT TRAVERZOID OFF OFF		ENTER	CLEAR WARNING EDIT WAR	NING SOUND ALAIM

7.5.2 Automatic correction

Utilization of this function is mainly related to previous function LAYER STOP. It allows you to correct wire guide position for all subsequent layers.



After the first layer is wound (eg. from left to the right), press the wire guide correction button and correct the wire guide position. This corrected position is saved by pressing SAVE AS RIGHT CORRECTION button. Likewise, insert and save the left correction after the second layer (from right to the left) is wound. For all the subsequent layers within this step these corrections will be made automatically.



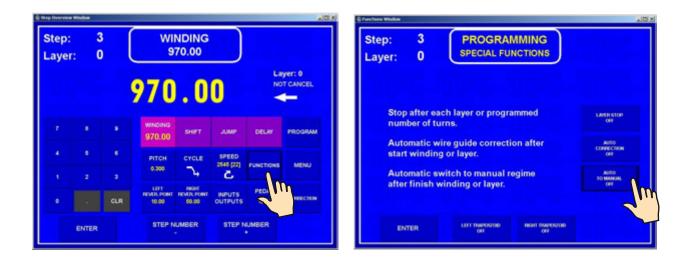


Maximum value for wire guide correction can not be greater than \pm 10 mm after a layer is wound. Value higher than this will be ignored !

7.5.5 Automatic switch to manual regime

This function will automatically switch manual regime after a certain pre-programmed number of turns have been completed.

In the manual regime the winding is done by the foot pedal. The value of the pitch is taken from the current step. The wire guide direction is controlled by WIRE GUIDE DIRECTION button. The number of turns wound in this regime is not defined.

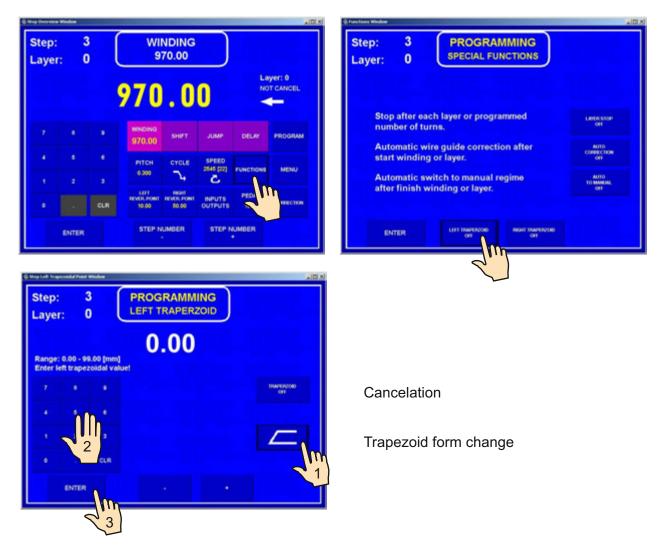


tep: 3 ayer: 0	PROGRAMMIN SPECIAL FUNCTION	
Stop after number of	each layer or programmed turns.	d Lene stor
	wire guide correction aft ing or layer.	er Auto convection
	switch to manual regime winding or layer.	AUTO TO MANNALAEL OW

Pressing of button "STOP" ends manual regime and programme continues in automatic regime.

7.5.4 Trapezoidal winding

This function automatically shifts the reversal points after each layer is wound.

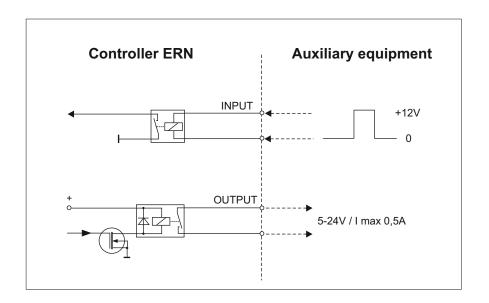


Available form of trapezoidal windings :

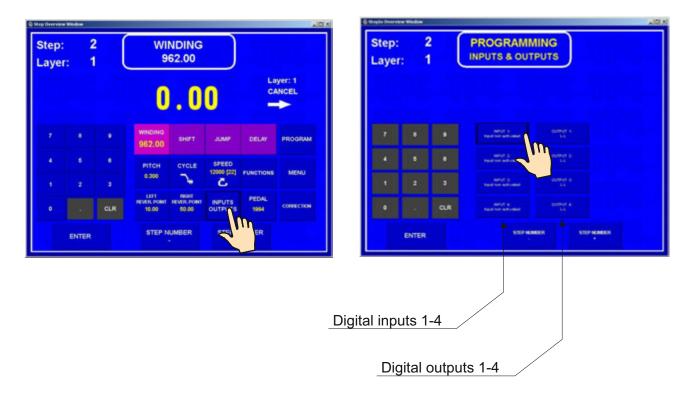
	left trapezoid : OFF	right trapezoid : / X,X
\square	left trapezoid : OFF	right trapezoid : \ X,X
\searrow	left trapezoid : \ X,X	right trapezoid : OFF
	left trapezoid : / X,X	right trapezoid : OFF
\searrow	left trapezoid : \ X,X	right trapezoid : /X,X
\square	left trapezoid : / X,X	right trapezoid : \ X,X
\searrow	left trapezoid : \ X,X	right trapezoid : \ X,X
	left trapezoid : / X,X	right trapezoid : / X,X

7.6 Auxiliary inputs and outputs

Machine provides an oportunity to program and control up to 4 auxiliary digital outputs and 4 digital inputs. Digital inputs and outputs are galvanically isolated. Relay is applied in standard equipment.



7.6.1 Window for inputs and outputs



7.6.2 Digital inputs programming

Step: Layer:	1		PROGR/)		Step: Layer	2 : 1		PROGR/ INPI)	
7			Martin 1 Name Annual canad	and the state of the	NAVE 3 Next tornardivated	NATURA A Nacal National Contract				APUT 1 aput romationized	and the state of the	res ^{ter} t des	No. Contraction
	6		manufi n Cycle anan	parties a Optimised	overset al. Cycle allert	Contraction		6		Called and	antot p Cycle start	indraff it. Cyclin dael	tempt a Cycle stat
•	2	3	antoli i Cycla Hamighter	naturi () Cysia marradian	naturi 3 Casta estastigation	National Cycles infernation	-	2	3	m	named () Cyclic coloringtion	adıştış. İşde Herişkini	Nerof a Cycle reservatio
0		CLR	mathoff (1) Cyclic attact blockback	neryf 3 Cysle stef binnied	nation a Cyclic start biochast	indry's a Cysica algorithmic and	۰		CLR	Comment	named a Cycle shert tracked	andruff () Cycles allert blocked	ndroff a Cycle aller Monte
	ENTER			NOP NUMBER	STOP NUMBER			ENTER			TEP NUMBER	STOP NOMED	

Each digital input can be programmed as:

INPUT NON-ACTIVITED - input is inactive

CYCLE INTERRUPTION - winding cycle interrupton is done if input is high (+ 12 V)

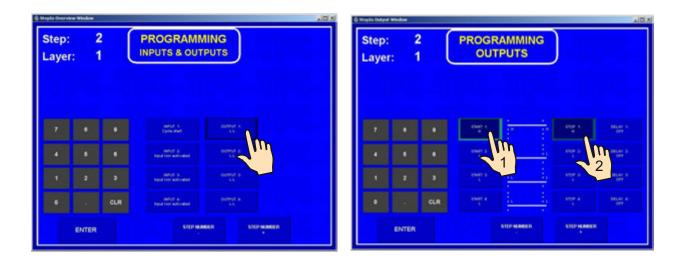
CYCLE START - winding cycle start is done if input is high (+12 V)

CYCLE START BLOCKED - start is blocked while duration of high (+ 12V)

7.6.3 Digital outputs programming

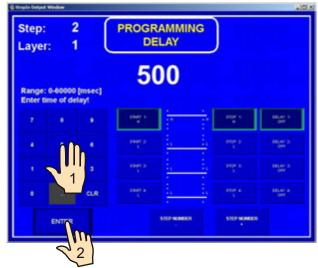
The following 3 parameters can be programmed in digital outputs 1 - 4:

- level of output after step start up (L relay on, H relay off)
- level of output after step finish up (L relay on, H relay off)
- delay of output action



Delay

Step: _ayer			PROGR	RAMMI			
		•	that s	1	-1	ng s	Mare 1 SH
•	5	٠	enset 2			1008 E 1	AN AN A
•	2	•	enser a				00.40 S.
0		CLR	mar a -	<u> </u>	-	ann e	10.47 A 011
	ENTER			STEPNARD		STIP NUMBER	



	2 1 (AMMING PUTS)		Step: Layer:	2		PROGRAMM		
7 8	•	stage is		ange e	DELEY S DOI (Hotel)	7			annut s Cycle alert	Contract in a	
4 8	٠	etion a	<u>i.</u>	erter p	BELAY S. GH	•			NATURA 2 National Addresses	000000 B	
1 2	3	attact a			BELIEV S. OFF		2	3	antist 3 april torr activated	overse a	
•	CLR	attan a	<u>i.</u>	erres a	DELAT A	•		CLR	MATCH & Figure for anticipant	overe +	
ENTER			STEPHENER	STEP NUMBER			ENTER		STOPMA	-	

8. STEPS LIST

Steps list displays view of programmed steps and provides the following possibility for programming and corrections.



								962
	22.80	100				7.		
1	22.00 • column	0.580	6 mill	10.00 (K	22.80 -++	~ +		
	120.00	100				5.		
	3.00	0.000	e	10.00 (8	22.60 -+)	~ +		
	10.00	100				5.		
	25.00 + cmcm	0.500	101 C 0.00	10.00 K++	22.60 ->	D +		
	120.00	100				D +		
	0.00 ➡	0.000	6 and	10.00 K+-	22.80 ->	р,		
	10.00	100				5.		
	25.00	0.500	101 C (101	10.00 K-r	22.60 ->)	~ +		

- Parameter correction

									962
	22.60	100				~ +			
<u>.</u>	22.00	Î	6 a.m	10.00 (K	22.60 -9	~ ,			1
	120.00	100				Ъ.			
	3.00 + L-5	0.000	e	10.00 Km	22.50 ~>	~ ,			t
	10.00	100				n .			
	25.00	0.500	6 a.22	10.00 jil-+	22.80 ->	р.			1
	120.00	100				1			
	9.00	0.000	e	10.00 (5++	22.60 -++	~ +			1
	10.00	100				~ .			1
	25.00	0.500	191 C (101	10.00 K++	22.60 ->	∽.			
	LOSE	ange women			CORV 1714		-	-	

49 / ERN T / V 1.3

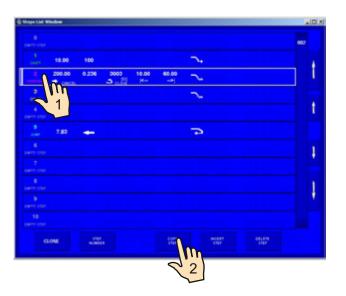
step:	2		RAMMI	NG		
tange: 0.00	00 - 40.000 (r		000)		
		WINCING 780,00	SHIFT	JUMP	DELAY	PROGRAM
•		РІТСН 0,000	CYCLE	SPEED 1964 [12]	FUNCTIONS	MENU
	1 1	HITT HENTR POINT 0.00	IBGHT PENTR POINT 0.001	INPUTS OUTPUTS	PEDAL	сонистон
EN		8				
EN			9		•	

Each parameter can be changed in this way.

- Insert empty step



- Copy step



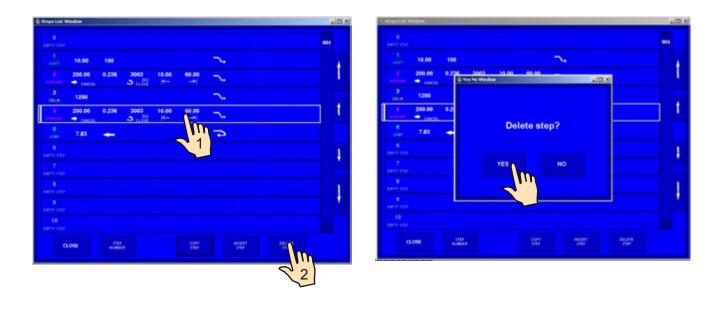




Pressing of button "COPY STEP" ends copying.

								004
	10.00	100				D +		
	200.00	0.236	0000 131	10.00 K	60.00 -#	\sim		
3 00.4	1200					\sim		
-	200.00	0.226	3000 5 colisi	10.00 Km	60.00 ->	~ .		
8 3088	7.80	-				-		

- Delete step





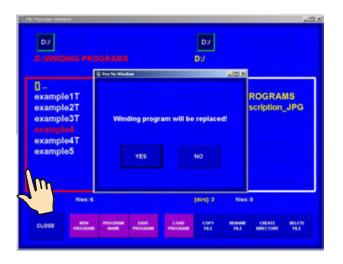
9. PROGRAMME SAVING AND OPENING

T-version is equipped with computer control with touch screen and Windows . SSD is used as the storage medium. PC memory space is divided into two partitions C: and D:. The operating system is installed on C:. Access to partition C: is blocked. Partition D: is used for manufacturer application programmes and winding programmes. This can be accessed and modified.



9.1 Programme opening

Step: 0 Layer:						D. ANEGRA PROGRAMS		ру D:/
	0	. 0	0			0 example1T example2T	1	TPC WINDING PROGRAMS Winding_Description_JPG
7. (0) 9	WINDING	SHIFT	JUMP	DELAY	PROGRAM	example3T exampled exampled	Martin (Martinetter) (247	
• • •	ртсн	CYCLE	SPEED	Functions		examp 1		
• · · ·	t RUAR.PORT	REALT FORM	INPUTS OUTPUTS	PEDAL 1994	CONVECTION	(ars) 0 Nex: 6	+	(Ans):0 Mesco
ENTER	STEP N	UMBER	STEP N				ANT LOAD	COPY HEMANE CHEATE HELFTE PRZ PRZ HEMICONY PRZ







9.2 Programme saving

Each programme can have a maximum of 350 steps. Once a programme is created it can then be saved. Provide a name for the programme and save it into directory (or subdirectory).

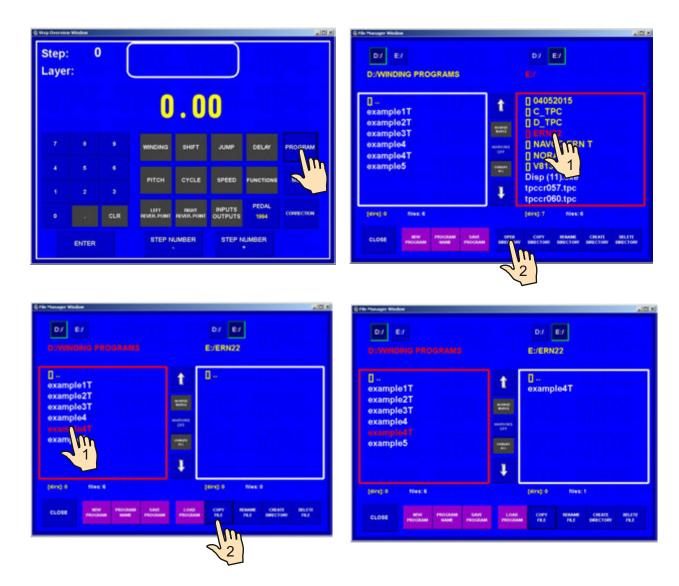






D:/WING				D:/				
0 example1T example2T example3T example4 example4T			t	t FIRMWARE				
			WINDING PROGRAM					
			essences: One					
example5 example_61			-					
				1				
(6/rs): 0	Nes:7				(des) 4	files:	•	
		PROCEME	144	1.040	c	-	CREATE	MATT

9.3 Programme copy



This function allows to copy programmes already created.

10. MENU

Displays and allows the change of some basic settings of the machine.



10.1 Programme locking

Programming can be locked or unlocked by entering MASTER or PIN code. Corrections which are performed during the winding process (wire guide correction, back winding, abort step etc.) are not blocked.

-		MACHINE	u J	MART DECEMBER	-102			MACHINE		HER.
100			-							040,00000 00000 00000
		Model: Gear:	ERN-22 12000 [rpm]	CHANGE CHANGE	т	•		Model: Gear:	ERN-22 12000 [rpm]	LANGUAGE Distance Pix CODE
•		Max. width: Number:	210.00 [mm] 0	MACKING MUMBER				Max. width: Number:	210.00 [mm] 0	Machine Montelle
		License: Version:	1024 058.065.920	Large sciences		2		License: Version:	1024 058.065.920	LATER MINISTER VIENUE
•	CLR		Apr 8 2015	EPHADU B SERIO POLITICA IE NEPT	•		CLR		Apr 8 2015	22NO PONTON 33NO PONTON 15 KEPT
		Operator:	operator 5	ACCELERATIONS DECISIONNONS	A CONTRACTOR			Operator:	operator 5	ACCELERATIONS DELECTIONS

10.2 Error messages

If mistakes occur, these will trigger the following error messages:

ERROR Microswitch

Mechanical displacement of the wire guide. It occurs if the lateral power on the wire guide overcomes the torque of the step motor. Solution: press RESET

ERROR Spindle speed versus pitch

Pitch or spindle speed is too high (exceeds the max.wire guide speed 75 mm/sec) Solution: press ENTER and correct either spindle speed or pitch

ERROR Wire guide position out of range

Winding width is out of range. Solution: press ENTER and correct either relative position or reversal points

ERROR Program is not logical

In the ContFAST cycle type if the programming is not logical, the next step can not be the shift, jump or winding with the opposite speed direction.

Digital control by CAN- bus provides the storage and display of errors of Servo Drive. Displayed errors are intended for service purposes.



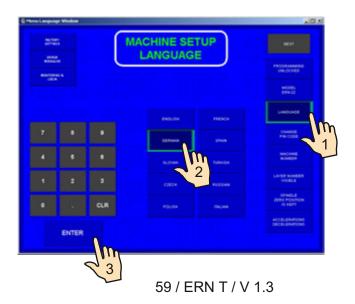
10.3 Model selection





10.4 Display language

Allows a selection of display language.



10.5 Winding machine number

Winding machine number can be set for easy network identification.

NUMP NUMP			MACHINE		
-	-				PROGRAMMING
(dia					MCCE) ERM-SOM
					LANDUADE
		٠	Model: Gear:	ERN-100K 600 [rpm]	Conincia Poin CODE
		٠	Max. width: Number:	210.00 [mm] 1	MACHINE NUMBER
1	2	•	License: Version:	1024 058.065.920	Langta sarranging
•		CLR		Apr 8 2015	EPINOLE 2540 POSITION 16 K0PT
			Operator:	operator 5	ACCELERATIONS DECELERATIONS

10.6 Access PIN code setting

Available codes for user :

- MASTER code allows you to change all settings in menu. This code is fixed by producer and is referred to guarantee certificate.
- PIN code lock and unlock programming. This code can be set by user in range 0 999999 Default : "0"



10.7 Zero spindle position mode



There are two possibilities for set :

- Absolute zero spindle position ON zero spindle position as set during reset is kept for all winding steps and manual spindle handling
- Absolute zero spindle position OFF zero spindle position starts at actual spindle position and the new one is always set by winding step START

11. FIRMWARE AND UPGRADE

Upgrade files can be delivered via e-mail.

- There are two types of upgrade files:
- tpccrxxx.tpc control board upgrade, where xxx is number of version (e.g. tpccr060.tpc)
- PC application programme upgrade

11.1. Upgrade of the application programme

Procedure of the application programme upgrade is as follows:

- copy (unpack) received upgrade file
- connect flash disc, keyboard and mouse to the USB ports of the PC
- close the winding application (for example CTRL +ALT+DEL)
- install upgrade in accordance with received instructions

11.2. Upgrade of the control board

Connect flash disc to the PC and load upgrade file tpccrxxx.tpc :





0 example1T example2T	C Tes No Window	X Dia	
example3T example4 example5	Firmware will be	replaced! NO	
pers) o meso		(den): 0 files:	

12. Creation and modification of the operator's list

Operator's name is used for the identification when production log is created. The names and codes information are stored in the file C:\TPC\OperatorNames.ini, this can be edited.

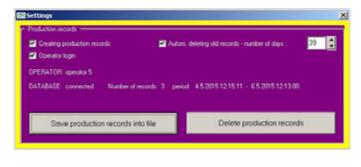
Edit Options Help InnaObs1shp]	100 %
wna00slung]	
operator 1	
operator 2	
operator 3	
operator k	
operator 5	
operator 6	
operator 7	
operator #	
operator 9	
operator #	

Note:

- never change the header, it has to remain on the first row, in the form [MenaObsluhy]
- all the following rows have to be in form: numerical code of the operator = name and surname of the operator, e. g. 127 = John Smith

13. Production log setting





13.1 Production log

Create log records - check this option if you want to monitor coil production

Operator login - check this option if you want to assign operator names

Delete old records automatically – check this option if you want the old records to be deleted automatically and set number of days after which records should be deleted

Save production log to file – production records will be saved to a XML file. After pressing the button a dialog box appears for the file saving and a preset file name is proposed: "TabProd_ERN_num_X", where X= numerical code of the winding machine. The production log can be transferred via the flash disc from the winding machine into the PC for further processing e.g. with the help of the MonitorERN programme.

Delete production log – all the records of the winding machine production will be deleted. If you do not use the function of the automatic deletion of the old records it is a good practise to save them to the xml file regularly, transfer it for further processing on the PC and delete them in the winding machine.

13.2 Terminal mode

Step 2 WINDING 2 CYCLE STATE CT INC 500.00 6000 8 TURNS 200.00 Position Gear: GRAM NAME: test 3 ABORT MIE GUDE 1 RE GUER Position: 51.11 t 1 inchest 1.5te Next Step: 1 - SHIFT Name: Pokus1 Pedal: PROGRAM

TERMINAL = displays winding instructions

Winding procedures are able to provide winding machine operators with additional important information on winding. If a winding programme is accompanied with a corresponding winding procedure a current winding step technological operation description is displayed on the winding machine monitor automatically. This information comes from the winding procedure and it can be represented in form of texts or images.

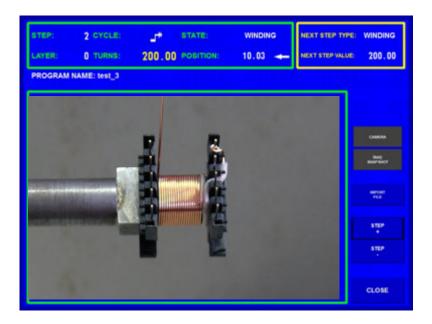
10.03

Application of the winding procedures can:

- support a technological discipline and reduce a frequency of operator failures according to ISO standards requirements

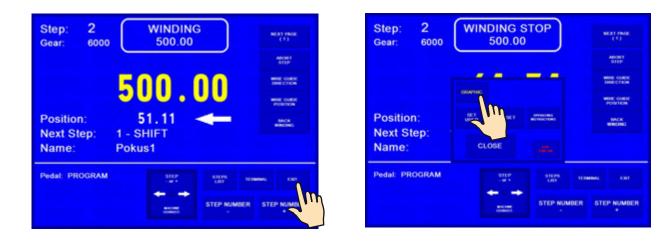
- help to change produced assortment operatively even in the case of complicated winding procedures

- quicken and simplify new personnel training



14. Software GRAPHIC

The GRAPHIC software is a comfortable design program, connected online with a winder. It allows the creation of complicated long programs with an overview of the position of the wire guide and has special features such as layer spread or correction.



	WINDING STOP	[2] Abort step	BOBBIN NAME
	Turns: 64.74	Position: 85.29	CONSTANT NAM
	Gear: 6000 L	AYER: 0 <<<	CONSTANT NAM
	- STEP: 2-		TYPE of STEP
	T. of CYCLE: End	LAYER 0	WINDING 1
	TURNS NUMB 500.00	TURNS: clear	<u> </u>
	LEFT REV 50.00	RIGHT REV: 100.00	WINDING 2
	PITCH (mm) 1.000	GUIDE DIR: →	SHIFT
	SPEED 5003	SPINDLE DIR: Iwt	<u> </u>
	ACCEL/DECEL 11	SHELD close	JUMP
	SPECIAL PUNCTIONS	INPUTS/OUTPUTS: IN_1: NA IN_2: NA IN_3: NA IN_4: NA	DELAY
(<u>*</u>		0UT_1 L-L 0UT_2 L-L 0UT_3 L-L 0UT_4 L-L	GEAR
97.7 [mm] CNUSE 110.0	STEP: 2	FUNCTION	ACTION

The operating instructions are supplied with the supplied USB key.

15. PACKAGE CONTENTS

ERN 100

Documents delivered with the machine:

1 pc certificate of quality and completeness

1 pc user's guide

Supplied Accessories:

2 pcs fuse T 315 mA/250 V

2 pcs fuse T 1,25 A/250 V

1 pc timing belt 5MR - 600 - 25

1 pc timing gear 60 5M 25 - 6W

3 pcs allen key

ERN 200

Documents delivered with the machine:

- 1 pc certificate of quality and completeness
- 1 pc user's guide

Supplied Accessories:

2 pcs fuse T 630 mA/250 V

2 pcs fuse T 1,25 A/250 V

1 pc timing gear 36 teeth

3 pcs allen key

16. FUSE CHANGE

Change the blown fuse. Note the main power plug must be disconnected. The fuses are on the back panel of the drive box. Be sure to only use a type of fuse specified by the manufacturer.

17. MAINTENANCE

As the machine contains a minimal number of mechanical gears, the maintenance is simple. To ensure trouble-free operation, the following steps are recommended:

the winding space should be regularly cleaned of dust, dirt and wire ends
tension of the timing belt should be checked regularly
Note: the ball bearings have permanent grease filling, no lubrication is needed

18. WARRANTY PERIOD AND SERVICE

Warranty period is 24 months from the date of delivery. Warranty and after warranty repairs are provided by the manufacturer.